Lecture 14 (summary)

In this lecture, we show how to set up an SDP program to search for a flag algebra proof. We will demonstrate the approach on the following specific example: show that $\cdot + \nabla \geq \alpha$ for α as large as possible. We first fix a number of vertices $n \in \mathbb{N}$, which is the size of graphs that we work with. In our example, n = 3 (the choice of *n* corresponds to the computational power that we may use). List all graphs G_1, \ldots, G_K with that *n* vertices. We can combine the following three types of expression to get the desired inequality: $G_i \geq 0$, $G_1 + \ldots + G_K = 1$, and $[v^T A v]$ where *A* is a positive semidefinite matrix and *v* is a vector with entries from \mathcal{A}^R for some root graph *R*, e.g, $R = \circ$ or $R = \infty$. As $G_1 + \ldots + G_K = 1$ can be viewed as $G_1 + \ldots + G_K \geq 1$ and $-G_1 - \ldots - G_K \geq -1$, we are then searching for non-negative coefficients for the inequalities and suitable positive semidefinite matrices.

Recall that a semidefinite program is an optimization problem that asks to maximize $\langle C|X\rangle$ subject to $\langle A_1|X\rangle = b_1, \ldots, \langle A_k|X\rangle = b_k$ over all positive semidefinite matrices X, where $\langle M|N\rangle$ for two matrices $M, N \in \mathbb{R}^{n,n}$ is the sum $M_{11}N_{11} + M_{12}N_{12} + \ldots + M_{nn}N_{nn}$. Note that if X is positive semidefinite matrix, then every diagonal entry of X is non-negative and more generally every principal submatrix is positive semidefinite. So, we dedicate some of the diagonal entries of X to be the sought coefficients for the inequalities and some of the principal submatrices to be the sought positive semidefinite matrices. The constraints $\langle A_1|X\rangle = b_1, \ldots, \langle A_k|X\rangle = b_k$ will then enforce the left hand side to as desired. Hence, we set k = K and the *i*-th constraint will force the coefficient at G_i .

In our example, we have the following inequalities to combine:

$$1 \leq \mathbf{\dot{v}} + \mathbf{\dot{v}} + \mathbf{\dot{V}} + \mathbf{\dot{\nabla}}$$
$$-1 \leq -\mathbf{\dot{v}} - \mathbf{\dot{v}} - \mathbf{\dot{\nabla}} - \mathbf{\dot{\nabla}}$$
$$0 \leq \mathbf{\dot{v}}$$
$$0 \leq \mathbf{\dot{\nabla}}$$
$$0 \leq \mathbf{\nabla}$$
$$0 \leq \mathbf{\nabla}$$
$$0 \leq \left[\begin{bmatrix} \mathbf{\dot{o}} \\ \mathbf{\dot{\delta}} \end{bmatrix}^T A \begin{bmatrix} \mathbf{\dot{o}} \\ \mathbf{\dot{\delta}} \end{bmatrix}, \end{bmatrix}$$

where A is positive semidefinite. Let γ^+ , γ^- , $\gamma_1, \ldots, \gamma_4$ be the sought coefficients for the first inequality, we will think of the matrix X as

$$X = \begin{bmatrix} \gamma^+ & & & & \\ & \gamma^- & & & & \\ & & \gamma_1 & & & \\ & & & \gamma_2 & & & \\ & & & & \gamma_3 & & \\ & & & & & \gamma_4 & & \\ & & & & & & A_{11} & A_{12} \\ & & & & & & A_{21} & A_{22} \end{bmatrix}.$$

Hence, the matrices A_1, \ldots, A_4 , the reals b_1, \ldots, b_4 and the matrix C will set as follows.

Running the program, we obtain that an optimal solution is the following matrix X:

, which yields that the sum of the following two inequalities

$$\frac{1}{4} \leq \frac{1}{4} \cdot \cdot + \frac{1}{4} \cdot \cdot +$$

gives the desired inequality, $\bullet \bullet + \nabla \ge 1/4$.